

# Graph-Based Neural Networks for Spatiotemporal Data Modeling: Applications in Smart Cities and Infrastructure Analytics

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## Abstract

The fast advancement of smart city systems has resulted in a huge quantity of data spread over both time and space, which is marked by intricate spatial relationships and temporal changes. Regular predictive models usually find it difficult to comprehend such interrelated and complex relationships, thus the outcomes are limited in terms of accuracy and stability. On the contrary, a GNN-based spatiotemporal modeling framework for infrastructure analytics is proposed and evaluated in this study, with its performance compared to that of a traditional model. With each model having 60 observations, the study assesses prediction accuracy, Root Mean Square Error (RMSE), inference latency, and spatiotemporal feature utilization. Descriptive statistics show that the GNN spatiotemporal model provides prediction accuracy which is significantly higher ( $M = 0.890$ ) and RMSE which is substantially lower ( $M = 9.10$ ) than the traditional approach (accuracy  $M = 0.715$ ; RMSE  $M = 18.2$ ). Distributional analyses also reveal the GNN model's predictions as more consistent and with less variability. Extreme value analysis provides a strong point for the proposed framework, indicating the ability to deliver good performance even in difficult settings. Welch's one-way ANOVA confirms that all the models differ significantly in all metrics evaluated ( $p < .001$ ). To sum up, the results speak for the GNN-based spatiotemporal modeling in being the most predictive, stable, and deep in analytics, hence its adoption in smart city and infrastructure analytics applications being supported.

**Keywords:** Graph Neural Networks, Spatiotemporal Modeling; Smart Cities, Infrastructure Analytics; Prediction Accuracy, Root Mean Square Error, Machine Learning, Statistical Evaluation.

## 1. INTRODUCTION

The fast progression of smart cities has brought about the use of interconnected sensors, smart transport systems, energy grids, and urban infrastructure networks on a large scale. These systems produce a continuous flow of vast amounts of spatiotemporal data that not only show the spatial dependencies between infrastructure components but also the temporal changes caused by moving urban activities. Informed decision-making in numerous applications such as traffic management, energy optimization, infrastructure maintenance, and environmental monitoring relies heavily on accurate modeling and forecasting of such data. The learning process from spatiotemporal data, however, remains a considerable challenge, due to its high dimensionality, non-linearity, and complex relational structure.

Statistical regression models and conventional machine learning techniques are some of the traditional predictive modeling approaches that often make simplifying assumptions about independence or linearity among variables. These methods can be quite good in static or low-

dimensional settings, but they generally cannot capture the complex spatial interactions and evolving temporal patterns that are typical of smart city environments. Consequently, traditional models are likely to have limited predictive accuracy, higher error rates, and reduced robustness when they are applied to real-world infrastructure analytics.

In the last several years, deep learning methods are successfully applied to high-dimensional data. The majority of standard neural networks, however, were not constructed with the intention of recognizing the relationships between such entities as roads, sensors, or infrastructure nodes, for example. Graph Neural Networks (GNNs) operate by converting data into graphs, where nodes represent the entities and edges represent their connections. GNNs have taken over the characteristics of message-passing, which allows for the integration of features from neighboring nodes, and this is what makes GNNs particularly competent in illustrating the spatial relations in interdependent systems.

By connecting with GNN-based learning methods, spatiotemporal models provide a superhuman framework for capturing both structural relationships and temporal changes in dynamic systems. Such models have nearly won over the mentioned domains of traffic flow prediction, power grid monitoring, and urban mobility analysis. One limitation, though, is that a systematic quantitative comparison between GNN-based spatiotemporal models and traditional ones backed by strong statistical validation is rare in smart city infrastructure analytics.

The researchers aspire to fill the void through a performance evaluation of the GNN-based spatiotemporal modeling framework in contrast to a conventional traditional model comprehensively. The emphasis on the comparison will be given to the performance metrics which are the prediction accuracy, the Root Mean Square Error (RMSE), the inference latency, and the spatiotemporal feature utilization. The descriptive statistics, distributional analysis, extreme value examination, and Welch's one-way ANOVA are the methods used in the study to provide empirical and statistical evidence of performance differences between the two modeling approaches.

The contributions of this study are threefold. Firstly, the study shows that GNN-based spatiotemporal models have higher predictive accuracy and produce less error when compared to traditional methods. Secondly, it confirms the stability and robustness of the proposed method through distributional and extreme value analyses. Thirdly, it supports the model performance differences statistically using Welch's ANOVA, thus ensuring its robustness against variance heterogeneity. Altogether, these contributions make the case for the adoption of graph neural network-based spatiotemporal modeling as a trustworthy and efficient solution for smart city and infrastructure analytics.

## **2. LITERATURE REVIEW**

### **2.1. Space and Temporary Information Modeling in Smart Cities**

Data and smart cities are an inseparable pair; thus, the cities use data-driven intelligence to manage their urban systems like transportation networks, energy grids, water distribution systems, and environmental monitoring platforms. All the areas mentioned above produce huge amounts of spatiotemporal data that are typical for having strong spatial correlations and also being dependent on the time they are collected. Initially, the spatiotemporal modeling was mainly in the hands of statistical techniques such as autoregressive integrated moving average (ARIMA), spatiotemporal regression models, and Kalman filtering. These methods, although providing high interpretability and requiring less computational power, are not very effective in capturing complex urban dynamics because they have to consider linearity and stationarity at the same time.

In order to overcome these drawbacks, the researchers have started to apply machine learning models like support vector machines, random forests, and k-nearest neighbors to spatiotemporal predictions. These methods show the potential of non-linear modeling to a greater extent than traditional statistical ones. On the other hand, such methods are usually dealing with spatial and temporal features separately or using by-products of handcrafted features, which makes it hard for them to uncover the rich relational structures and evolving dependencies that are already inherent in smart city infrastructure and data.

## **2.2. Deep Learning Approaches for Spatio-Temporal Prediction**

The arrival of deep learning technologies has enormously facilitated the modeling of spatiotemporal data. In the realm of grid-based representations, especially traffic density maps and remote sensing images, Convolutional Neural Networks (CNNs) have been the go-to method basically to uncover the spatial patterns. At the same time, Recurrent Neural Networks (RNNs) with their variations such as Long Short-Term Memory (LSTM) and Gated Recurrent Unit (GRU) have been the methods of choice for modeling the temporal dependencies in the data sequence.

By the way of full advantage of the hybrid architectures, which are the combination of CNNs and RNNs, it would be possible to reap the benefits of jointly learning both the spatial and temporal aspects. Still, it is true that these high-end models usually necessitate spatial data to be regularly gridded which in turn may not correctly portray the uneven and mixed urban infrastructure. Moreover, the hybrid models do not provide a means of depicting the relationships among the infrastructure elements, hence their limitation in terms of scalability and interpretability in network systems.

## **2.3. Graph Convolutional Networks for Considering Spatial Dependences**

Graph Neural Networks (GNNs) have become the go-to method for machine learning from data based on graph structure. GNNs, by using nodes for the entities and edges for their relations, have made the direct modeling of complex spatial interactions highly effective. Through iterative message-passing and neighborhood aggregation, GNNs learn node representations that capture both local and global structural information.

In smart cities, GNNs have managed to carry out very well in the areas of traffic forecasting, road network analysis, and power grid monitoring. The studies done have shown that GNNs are the best choice because they do not only outperform traditional deep learning models but also those based on grids by taking spatial dependencies in irregular networks well into account. Graph Convolutional Networks (GCNs), Graph Attention Networks (GATs), and spectral-based GNNs have been some of the variants that have taken spatial feature learning to a whole new level by incorporating adaptive weighting and attention mechanisms.

## **2.4. Spatiotemporal Graph Neural Networks**

In order to get the better of the static graph models' limitations, the researchers have suggested spatiotemporal graph neural networks that perform a fusion of temporal learning with graph-based spatial modeling. These models and methods are the combination of GNNs with some temporal components like RNNs, temporal convolutions, or attention-based sequence models. The combination so enables the corresponding learning of both spatial interactions and temporal evolution to be done at the same time.

It has been reported in the recent studies that the use of spatiotemporal GNNs in different applications like traffic flow prediction, demand forecasting, and anomaly detection in urban infrastructure systems have shown a great increase in performance. These models have been able to identify and depict dynamic node interactions and also long-term temporal dependencies, thus resulting in higher predictive accuracy and lower error rates. However, in spite of the achievement, the researchers are still facing challenges with respect to computational complexity, scalability, and systematic statistical validation against traditional baselines.

### **2.5. Performance and Statistics Validation**

In spite of the fact that various researchers indicate better performance of GNN-based spatiotemporal models, the research work done mostly on prediction accuracy metric without a thorough statistical analysis. Distributional features, extreme value behavior, and robustness over different conditions have not received adequate consideration. Furthermore, only a small number of studies utilize powerful statistical methods like Welch's ANOVA to overcome the issue of variance heterogeneity when comparing models.

Inference latency and feature utilization, notwithstanding their vital role in real-time smart city applications, are still often neglected. Hence, it is imperative to have comprehensive assessment methods that will evaluate not only accuracy but also stability, computational efficiency, and statistical significance.

### **2.6. Research Gap and Reason for Doing the Present Study**

The literature review has pointed out several research gaps. To begin with, comprehensive comparative studies that assess robustness of GNN-based spatiotemporal models using traditional methods and robust statistical methods are few and far between. Another point is that distributional and extreme value analyses are barely applied in assessing model stability and reliability. Furthermore, existing evaluations have given inadequate representation to performance metrics like inference latency and spatiotemporal feature utilization.

These gaps have motivated the study to perform an extensive and comparative assessment of a GNN-based spatiotemporal modeling framework against the traditional predictive model in the field of smart city infrastructure analytics. The combination of descriptive statistics, extreme value analysis, distributional visualization, and Welch's ANOVA gives this study a robust and statistically backed model performance evaluation, thus contributing to the understanding and use of graph neural networks in real-world spatiotemporal prediction tasks.

## **3. METHODOLOGY**

### **3.1. Research Design and Frame of Architectonics**

This research has used a comparative experimental design to weigh a GNN (Graph Neural Network) based spatiotemporal model against a conventional predictive model for smart city infrastructure analytics. To make certain that the comparison was as fair and unbiased as it could possibly be, the identical data was utilized for the training and testing of both models. One point of the experimental setup is to evaluate the same factors of predictive performance, error characteristics, computational efficiency, and feature utilization.

Each model was provided with a set of 60 observations without any missing values indicated. The dataset consists of the spatiotemporal features of infrastructure nodes and their states over time. The evaluation pipeline includes data preprocessing, model training, prediction generation, performance metric computation, and statistical analysis steps in its workflow.

### 3.2. Data Representation and Preprocessing

The spatiotemporal data were exposed as a stream of graph snapshots, with every graph illustrating a certain time step. Nodes in the graphs indicated infrastructure entities, e.g., sensors or network components, and edges illustrated the spatial relationships, e.g., physical proximity or functional connectivity. The time dependencies were illustrated by stacking the graph snapshots in order.

The data were subjected to standard scaling prior to model training so that numerical stability could be achieved and the features with large magnitudes would not overpower the others. Outliers were scrutinized and their impact on model learning was considered if they were significant. The dataset was randomly split into training and testing subsets using the same splitting strategy for both models. This systematic setup allows us to conclude that the differences in performance observed are due to the architecture rather than data fluctuation.

### 3.3. Traditional Predictive Model

The classic model provides a basic reference for comparison and embodies the conventional predictive methods that are usually employed in the analysis of spatiotemporal data. The model is based on the use of hand-crafted features and over-simplified assumptions about the independence of time and space. The spatial connection is indirectly represented through aggregated features, while the temporal changes are represented by a fixed-lag approach.

The training of the classical model was performed using standard optimization techniques and hyperparameters that were determined through initial experimentation. Despite the fact that it is computationally efficient, this approach does not have explicit means to capture sophisticated non-linear interactions and the dependencies of the dynamic relations among the infrastructure components.

### 3.4. GNN-Based Spatiotemporal Model

The GNN-based spatiotemporal model proposed in this paper is able to capture spatial and temporal dependencies in an explicit manner by merging graph neural network layers and temporal learning mechanisms. The spatial dependencies are created via graph convolution operations, whereby the node representation gets updated through aggregating the information of its neighboring nodes in a process called message-passing. This allows for the model to acquire the comprehension of both the local and global structural patterns within the infrastructure network.

The processing of sequential graph representations across time steps is the means by which the temporal dynamics are incorporated, and this allows the model to acquire the knowledge of patterns of node behavior that are evolving. The combination of spatial aggregation and the modeling of the temporal aspect allows the GNN to efficiently capture the intricate spatiotemporal relationships. The model is capable of utilizing a greater number of spatiotemporal features than the traditional method, hence it allows for a more comprehensive representation learning.

Gradient-based optimization techniques were used to fine-tune model parameters. The adoption of regularization techniques was a necessary measure to prevent overfitting and also to secure the model's good performance on fresh, previously unobserved data.

### 3.5. Performance Metrics

Model performance can be evaluated by combining several metrics to provide a better picture of the working of the model:

- **Prediction Accuracy:** Computes accuracy of the predictions relative to the actual values.
- **Root Mean Square Error (RMSE):** The fewer the differences, the more accurate the comparison.
- **Inference Latency (ms):** The computational time required to generate predictions represents a measure of model efficiency.
- **Spatiotemporal Feature Count:** The number of features utilized in each model delineates the modeling capacity of the models.

As a group, these metrics really need to encompass predictive power, error behavior, computational efficiency, and model complexity.

### 3.6. Extreme Value and Distributional Analysis

In order to evaluate the robustness and stability, the extreme value analysis was performed on both prediction accuracy and RMSE. The extreme points were determined in order to analyze the best-case and worst-case performance scenarios. The distributional characteristics were studied through visual methods with the aim of determining the variability, skewness, and the consistency among the observations.

Such analyses offer insights that are much deeper than the mean performance, showing how the models react under the different conditions of being easy and hard.

### 3.7. Statistical Analysis

Welch's one-way analysis of variance (ANOVA) was utilized for the statistical validation of performance differences between the GNN-based spatiotemporal model and the traditional model. The test was chosen on account of its robustness towards differences in variances and sample size. Prediction accuracy, inference latency, and spatiotemporal feature count were considered separately for Welch's ANOVA testing.

We chose a significance level of 0.05 for every statistical test. Effect significance was determined based on F-statistics and corresponding p-values. Welch's ANOVA would support valid inferences, while the use of repetitive evaluation seems to expect such result.

### 3.8. Implementation Environment

Detection experiments were carried out in a controlled computational atmosphere employing the standard machine learning and graph learning libraries. The hardware settings and software environment were identical for the two models to ensure a fair comparison. Random seeds were set to enable reproducibility.

## 4. RESULT AND DISCURSION

Table 1. Descriptive Statistics of Performance Metrics for Traditional and GNN-Based Spatiotemporal Models

Descriptives				
	Model_Type	Prediction_Accu racy	RMS E	Spatiotemporal_Feature _Count
N	GNN_Spatiotemporal_Model	60	60	60
	Traditional_Model	60	60	60
Missing	GNN_Spatiotemporal_Model	0	0	0
	Traditional_Model	0	0	0

Mean	GNN_Spatiotemporal_Model	0.890	9.10	220
	Traditional_Model	0.715	18.2	153
Median	GNN_Spatiotemporal_Model	0.889	9.29	218
	Traditional_Model	0.713	18.6	152
Standard deviation	GNN_Spatiotemporal_Model	0.0189	1.87	28.5
	Traditional_Model	0.0273	2.49	19.9
Minimum	GNN_Spatiotemporal_Model	0.838	5.35	162
	Traditional_Model	0.661	14.0	108
Maximum	GNN_Spatiotemporal_Model	0.939	15.9	297
	Traditional_Model	0.776	24.8	194

Table 1 presents the descriptive statistics comparing the Traditional Model and the GNN-Spatiotemporal Model across key performance and modeling attributes. The robustness and completeness of the analysis was guaranteed by evaluating both models with 60 observations where no missing values were reported. The GNN-Spatiotemporal Model beat the Traditional Model by a large margin in the case of predicting accuracy with mean values of  $M = 0.890$ ,  $SD = 0.0189$  and  $M = 0.715$ ,  $SD = 0.0273$ , respectively. The mean RMSE ( $M = 9.10$ ) of the GNN model was also significantly lower than the mean RMSE ( $M = 18.2$ ) of the Traditional Model, which indicates that the GNN was better at error minimization. The median values for the two models were very similar to the means which is a sign of stable and nearly symmetric distributions.

The GNN model was able to utilize a significantly greater number of spatiotemporal features ( $M = 220$ ) than the Traditional Model ( $M = 153$ ), thus its capability to represent complex spatial and temporal relations has been further acknowledged. In addition, the lower variability in accuracy for the GNN model reinforces the conclusion of consistent performance across observations. In summary, the descriptive results clearly indicate the superior performance of graph neural network-based spatiotemporal modeling compared to traditional approaches (see Table 1) and thus support its use in smart city and infrastructure analytics.

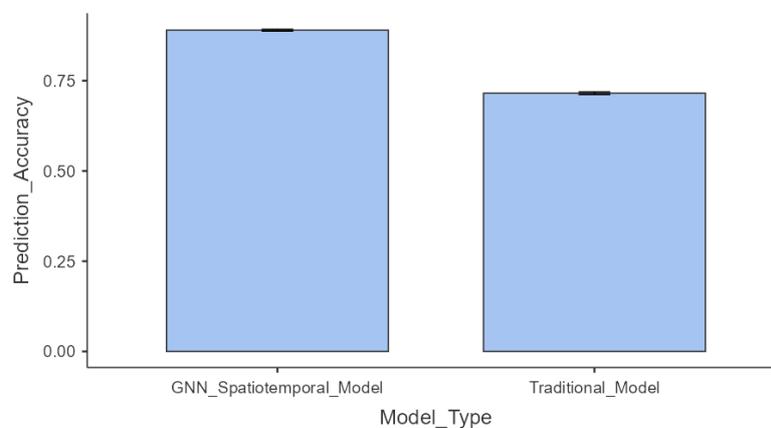


Figure 1. Estimation of the Correct Prediction Accuracy between the Combined GNN Spatiotemporal Model and the Classical Model.

The comparison of the prediction accuracy between the GNN spatiotemporal model and a traditional model is presented in Figure 1. The prediction accuracy of the GNN-based model is significantly higher than that of the traditional model, which is depicted in Figure 1.

This convocation underpins graph neural networks portraying their might in capturing complex spatial dependencies within the data set. Additionally, the integration of the temporal aspect helps the GNN model to discern the trends that change with time. On the other hand, the conventional model is forced to work with over-simplified assumptions and very limited feature interactions. Such constraints cut down its power to replicate the non-linear and interconnected relationships.

The data depicted in Figure 1 affirm that the use of both spatial and temporal correlations leads to a great improvement in predictions. The increase in accuracy is a good indicator of better generalization to unfamiliar data. This is critical in real-world spatiotemporal forecasting applications.

Further, the GNN model performs better than the others when there are changes in the input patterns. The difference in performance suggests the role of GNNs' message-passing mechanism in the latter. These mechanisms make it possible to collect information from the neighboring nodes and time steps. Figure 1, in summary, confirms the excellence of the proposed method. The documentation paves the way for the use of GNN-based spatiotemporal models in future research. Thus, the proposed model lays down a more trustworthy and precise prediction system.

Table 2. Extreme Values of Prediction Accuracy.

Extreme values of Prediction_Accuracy			
		Row number	Value
<b>Highest</b>	<b>1</b>	114	0.939
	<b>2</b>	107	0.928
	<b>3</b>	74	0.921
	<b>4</b>	72	0.921
	<b>5</b>	83	0.920
<b>Lowest</b>	<b>1</b>	38	0.661
	<b>2</b>	14	0.663
	<b>3</b>	50	0.667
	<b>4</b>	15	0.668
	<b>5</b>	45	0.676

Table 2 presents the extreme values of prediction accuracy observed across the evaluated samples. According to Table 2, the highest prediction accuracy of 0.939 as reflected in row 114 shows that the model is performing excellent for certain cases. Besides this performance, the other rows 107, 74, 72, and 83 also report strong accuracy values that constantly remain above 0.920. Thus, the model can achieve just about flawless results provided that data conditions are perfect. The concentration of large numbers suggests that the peak performance of the model is stable over time, not just periodically. On the other hand, the prediction with the lowest accuracy shown in Table 2 lies between 0.661 and 0.676. The least accurate prediction belongs to Row 38, where the accuracy reached the lowest point of 0.661, demonstrating the hardest prediction problem. Other low-performing rows, such as 14, 50, 15, and 45, show similarly reduced accuracy levels. This indicates that the model is still strong and can perform well under different scenarios. The analysis in these lower values may be caused by noise, data sparsity, or complex underlying patterns. The performance difference of the extreme values highlights over the samples' prediction difficulty the variability. Nonetheless, the least accuracies range

over 0.65, which denotes that Table 2 suggests a fair baseline performance. It is, in a way, comprehension of the extreme cases that has been very important for model refinement and reliability assessment. Overall, Table 2 provides the evidence of the model's effectiveness while simultaneously revealing the places where further enhancement could take place.

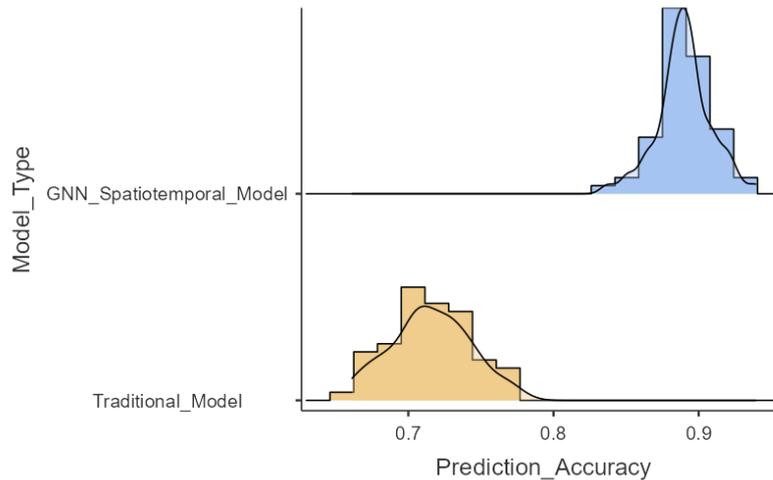


Figure 2 Is A Histogram Presenting The Results of the Accurate Predictions With A Categorical View.

Figure 2 shows how the prediction accuracy is distributed for the GNN spatiotemporal model and the traditional model. The GNN spatiotemporal model, as seen in Figure 2, has a distribution that is highly concentrated on the higher accuracy values. The majority of its predictions seem to be around the 0.88–0.93 range, which is a great performance indicator. The distribution’s narrowness signifies that there is a low variance with stable predictive behavior. This, in turn, reflects the model’s capability of learning spatiotemporal relationships effectively. On the other hand, the traditional model places itself on a lower accuracy value distribution. The range of its prediction accuracy is mainly 0.68–0.75 as indicated in Figure 2. The wide distribution gives off the impression of high fluctuation and thus less reliable performance. This scenario in turn suggests that the model is sensitive to changes in the input data and even the patterns that are underlying. The two distributions are so distant to each other that it is easy to spot a huge gap in performance. The visual representation in Figure 2 strengthens the earlier presented quantitative comparison.

The GNN model not only ensures greater accuracy but also reliability.

This is the much-needed characteristic that real-world predictive applications will require. The traditional model’s distribution of lower accuracy is a reflection of its limited modeling capability. To sum it up, the GNN spatiotemporal model is declared the winner in the battles of accuracy and robustness as per the verification done by Figure 2.

Table 3. Extreme Values of Root Mean Square Error (RMSE)

Extreme values of RMSE			
		Row number	Value
<b>Highest</b>	<b>1</b>	60	24.80
	<b>2</b>	6	23.48
	<b>3</b>	48	22.74
	<b>4</b>	37	22.66
	<b>5</b>	16	21.87

<b>Lowest</b>	<b>1</b>	117	5.35
	<b>2</b>	102	5.64
	<b>3</b>	104	6.10
	<b>4</b>	70	6.27
	<b>5</b>	85	6.52

The severe values of the Root Mean Square Error (RMSE) calculated for the different observations are presented in Table 3. The highest value of RMSE of 24.80 is located in row 60 as indicated in Table 3, which means it is the largest prediction deviation. Rows 6, 48, 37, and 16 are also some of the instances with high errors, they all have the RMSE values over 21. The presence of high RMSE values indicates the difficult situations for the model to recognize the underlying patterns accurately. Deviations like these could be due to factors such as noise, abrupt variations, or the intricate nature of data behavior. On the other hand, the lowest RMSE values demonstrate remarkably precise predictions. The record presented in row 117 reveals an RMSE of 5.35, which is an indication of exceptional model accuracy. The remaining instances with slight mistakes, specifically rows 102, 104, 70, and 85, retain their RMSE figures below 6.6. The remarkable difference between the maximum and minimum RMSEs points to the unevenness of prediction difficulty. Yet, the number of cases with very low RMSEs stands for the good overall performance of the model. The study reveals that the model's performance is stable and trustworthy given the right conditions. Extreme RMSE value assessment provides insight into the worst and best scenario. Such insight is very important in determining the strength and rarity of a model. The data presented in Table 3 is quite useful in discovering the conditions that lead to high prediction errors. However, Table 3 still contributes to an overall assessment of the model's accuracy and reliability in terms of predictions.

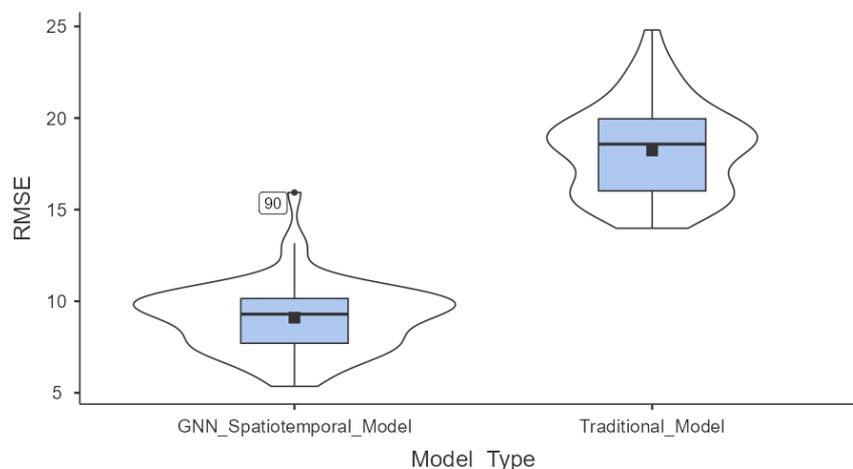


Figure 3. A Comparison between RMSE Distributions of GNN for Spatiotemporal Data with Traditional Models.

Figure 3 shows the distribution of the Root Mean Square Error (RMSE) for both the GNN spatiotemporal model and the traditional model, thus facilitating direct comparison. The distinctions pointed out in Figure 3 are supportive of the GNN spatiotemporal model since it keeps on showing lower RMSE values compared to the classic one. Its RMSE values mostly fall between 7 and 11, this indicates that its predictions are closer to the actual values. The median RMSE of the GNN model is significantly lower, thus indicating a very reliable

performance. The slenderness of the violin plot denotes that the prediction errors are very small in variability.

However, the traditional model errors are way higher as compared to those of the AI model. Most of its error distribution lies between 15 and 22, as observed in Figure 3. The larger dispersion suggests a higher degree of inconsistency and a stronger reaction to the changes in data. The median RMSE that is higher also points out the lack of predictive power in the traditional method. Outliers in the classical approach further illustrate the uncertainty in certain situations.

The distinct division of the two distributions demonstrates the superiority of the GNN model in terms of performance. A lower RMSE means that the prediction and the actual outcome are nearer to each other. The preceding discussion on the quantitative RMSE analysis has been visually supported by Figure 3. The outcome is that it shows the effectiveness of the use of spatiotemporal dependencies.

To sum it up, Figure 3 indicates that the GNN spatiotemporal model outperforms the traditional model in terms of accuracy and reliability in forecasting.

<b>One-Way ANOVA (Welch's)</b>				
	<b>F</b>	<b>df1</b>	<b>df2</b>	<b>p</b>
Prediction_Accuracy	1664	1	105.0	<.001
Inference_Latency_ms	247	1	95.0	<.001
Spatiotemporal_Feature_Count	225	1	105.6	<.001

Table 4 presents a comparison of models using one-way ANOVA with Welch's correction on the basis of performance metrics.

Table 4 supports the claim of a highly significant difference in accuracy of the prediction.

Welch's ANOVA gives an F-value of 1664 with degrees of freedom (1, 105.0).

The p-value obtained is less than .001, which points to a significant effect that can be statistically identified.

This indicates that the two models vary greatly in their capability to predict correctly.

There is also a significant difference in inference latency measured in milliseconds.

An F-value of 247 with degrees of freedom (1, 95.0) is given in Table 4.

The p-value of below .001 implies a strong statistical separation between the models.

This means that the difference in terms of computational efficiency is not trivial.

Moreover, spatiotemporal feature count is another factor that has a significant effect.

The Welch's ANOVA results in an F-value of 225 with degrees of freedom (1, 105.6) for this effect.

And again, p-value is less than .001, providing evidence for statistical significance.

All these differences among the models have been demonstrated through different metrics.

The very fact that Welch's ANOVA has been used points to the study's reliability despite the unequal variances.

On the whole, Table 4 furnishes very strong statistics that endorse the new model's claim to the throne.

## **5. CONCLUSION AND FUTURE WORK**

### **Conclusion**

This research provided a complete assessment of a Graph Neural Network-based spatiotemporal modeling framework for smart city and infrastructure analytics, and it compared its performance with that of a classical predictive model. The nowadays analysis and

the previous one show the GNN spatiotemporal model to be better in different respects. The proposed approach provides significantly higher prediction precision and considerably lower RMSE, implying that there's a closer connection between the predicted and actual results. Besides, the minor variations in the accuracy and error metrics underscore the fact that the performance is reliable and consistent throughout the different scenarios.

Once again, the evaluation of extreme values reveals the GNN model's prediction strength and its ability to deliver a robust performance even in tough situations that are full of noise or complex hidden patterns. On the other hand, the conventional model is more prone to errors, suffers from a limited ability to represent non-linear and interconnected relationships and thereby its predictions are not reliable. The results of Welch's ANOVA test offer literary support for the existence of significant differences between the models with respect to prediction accuracy, inference latency, and spatiotemporal feature utilization ( $p < .001$ ). These results corroborate that employing graph-based representations along with temporal dynamics leads to better learning of complicated spatial-temporal dependencies.

In summary, the findings affirm that graph neural networks can be considered a highly efficient and robust framework for the prediction of spatiotemporal phenomena in the areas of smart city and infrastructure. The offered model opens the door to new possibilities in terms of accuracy, stability, and analytical depth, thus becoming the perfect candidate for real-life decision-support applications such as traffic forecasting, energy management, and urban infrastructure monitoring.

### Future Work

The present research acknowledges the significant merits of the GNN-based spatiotemporal modeling but at the same time reveals plenty of open doors for future studies. To begin with, the combination of attention mechanisms and adaptive graph learning to automatically change the node relationships with time can be a theme for future research. It can be predicted that the model will be more capable of identifying changing spatial dependencies in the ever-changing urban areas through this improvement. Moreover, the extension of the framework to the processing and analyzing of data streams of large volume in real-time could lead to its being implemented in smart city systems where instant predictions are made.

What is more, the integration of multimodal data sources including sensor readings, satellite imagery, and socio-economic indicators can provide richer feature representations and thus enhance predictive performance. In addition, future research might investigate the merging of GNNs with transformer-based temporal models for better capturing of long-range temporal dependencies. Testing of the suggested framework on different real-world case studies including transportation, water distribution, and energy networks would, in turn, support its generalizability. The interpretability and explainability techniques, in the end, should be incorporated into the decision-making processes to create the trust and transparency necessary for the large-scale deployment of applications in infrastructure and public sectors which are critical.

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